

RATING THE EFFECTIVENESS OF BEAM AND SUCKER ROD PUMPING MODES

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One of the most helpful and convenient aids in the successful application of conventional beam pumping units is the American Petroleum Institute bulletin, 11L-3, "SUCKER ROD PUMPING SYSTEM DESIGN BOOK".

Expanding the work of Sucker Rod Pumping Research Inc. and the Midwest Research Institute, the API produced this set of tables (11L3) containing literally thousands of different precalculated pumping options, or modes, generated by using a model of the wave equation applied to sucker rod pumping when using conventional beam units.

These API tables have been widely accepted, and though certain sections have been questioned, and in some cases revised - in general, they have made a substantial contribution to the petroleum industry in facilitating the application of conventional pumping units.

According to these tables, there are twenty API approved sucker rod sizes, eighteen approved stroke lengths, and ten different API plunger diameters. Thus, in lifting a given amount of fluid from a particular depth, with a conventional pumping unit, theoretically there could be some 3600 beam and sucker rod system options, or pumping modes, for a single, artificial lift application - not considering variation in pumping speed.

Obviously, some of these thousands of pumping modes are either impractical, uneconomical, or both - but even the elimination of 90% of them still leaves over 350 pumping modes to consider.

In the API-11L3 design tables, for a single application, i.e. lifting 400 barrels per day from 3500 feet, requires the theoretical evaluation of nearly four hundred different pumping modes. Other applications require the consideration of even more than four hundred.

But which of these hundreds of pumping modes is the most effective as regards economy, longevity, and efficiency? Theoretically, any one of them can do the job - but which one is best?

Perhaps the "best pumping mode" is in the eye of the operator - but often consideration is given to the pumping mode having the lowest torque, or lowest rod or structural loading, or highest efficiency, etc. But the pumping mode having the lowest torque, might not be the most efficient, nor the mode resulting in the lowest rod loading might not afford maximum economy, etc.

Thus, the question arises, "What is the best and most effective pumping mode, when considering all, or most, of the dominant factors involved?"

PAST RATING CONCEPTS

A significant approach to optimum pumping mode selection was made in 1975 when Manuel Estrada, an outstanding researcher at the University of Tulsa, presented a thesis on, "Design and Optimizing Tables for the Mark II Oil Field Pumping Unit".

Included in this study was a section on an Economic Index (EI) which, according to the author, "gives the most economical pumping combination when considering torsional,

structural, prime mover, and lifting requirements." Estrada goes on to say, "By selecting the lowest EI number, the most economical pumping system is defined". Estrada's equation for the Economic Index is:

$$EI = 10^{-7} \frac{W_{\max} T_P P_{PR}}{LE}$$

WHERE: W_{\max} = Peak Polished Rod Load
 T_P = Peak Torque (In Balance)
 P_{PR} = Polished Rod Horsepower
 LE = Lift Efficiency

This is a simple and direct equation, relating some of the important variables of the beam pumping system, and casting them into a series of index numbers, each associated with a particular pumping mode. (Table No. 1)

Sometime later (1980) Louis Valera M, another researcher at the University of Tulsa developed a thesis entitled, "A Technique for Determining Optimum Geometry and the Most Economical Pumping Mode for Different Beam and Sucker Rod Systems". Included in this thesis was an extension and refinement of the Estrada pumping mode index, and Valera entitled his rating number, "The Comparative Economic Index (CEI)". He states, "Since the overall economy of a beam and sucker rod pumping system is a direct function of PPRL, PT, nameplate horsepower (HPNP), the cyclic load factor, and an inverse function of lift efficiency, it is logical to combine them into a simple mathematical expression such as:

$$CEI = 10^{-9} \times \frac{PPRL \times PT \times HPNP \times CLF}{LE}$$

WHERE: PPRL = Peak Polished Rod Load (lbs.)
 PT = Peak Torque in lbs. (in-balance)
 $HPNP$ = Nameplate Horsepower
 CLF = Cyclic Load Factor
 LE = Lift Efficiency

Valera further states, "A weight of 1.0 was given to each of the five variables used to calculate CEI values. Wherever experience dictates, the weighting can be done empirically. For instance, in an area where power costs are excessively high, the CLF could be weighted greater than one. For a given situation, the selection of the lowest CEI assures maximum economy." (Table Nos. 2a and 2b)

In 1982, a third thesis was authored by Solomon D. Lekia, which not only expanded, but refined the work of Estrada and Valera. Lekia's thesis was entitled, "An Improved Technique for Evaluating Performance Characteristics and Economy of the Conventional and Mark II Beam and Sucker Rod Pumping Systems". The designation that Lekia used for indexing the various pumping modes was called The Performance Index (PIX) which he states is, "an important number in evaluating the overall economy of a beam and sucker rod pumping system." It is given conceptually as follows:

$$\text{PIX} = 10^{-8} \frac{\text{PPRL} \times \text{PT} \times \text{HPNP} \times \text{CLF}}{\text{LE} \times \text{ITE}}$$

WHERE: PPRL = Peak Polished Rod Load (lbs.)
 PT = Peak Torque in-lbs. (in-balance)
 HPNP = Nameplate Horsepower
 CLF = Cyclic Load Factor
 LE = Lift Efficiency
 ITE = Index of Torsional Effectiveness

A power of one is given to each of the six variables to weight them equally. Peak polished rod load, peak torque, nameplate horsepower, and cyclic load factor appear in the numerator in order to keep their value as low as possible on various installations; conversely lift efficiency (LE) and index of torsional effectiveness (ITE) appear in the denominator because high lift efficiencies (LE) and indices of torsional effectiveness (ITE) are indicative of good pumping operations.

For a given design situation or application, selection of the lowest PIX value assures maximum economy. (Tables nos. 3a and 3b)

The work of Estrada, Valera, and Lekia are important concepts, expansions, and refinements for developing a valid procedure for selecting the optimum pumping mode for a beam and sucker rod pumping application.

Often, in the past, pumping units have been applied considering one, or perhaps two major variables, such as peak torque, or peak polished rod load, etc. One virtue of the indexing of pumping modes is that most of the important variables can be considered in the formulation - not just one or two.

Although there are many different modes for the venerable conventional pumping unit, it was not until the 1920's that a significantly different beam unit geometry, the air balance unit, became popular - with its own spectrum of pumping modes.

With the advent of the Mark II pumping unit in the mid 1950's, a third menu of pumping mode possibilities was added. As the Mark II patents expired in the late '70's, other beam pumping geometries appeared with their own unique series of modes, further adding to the vast number of pumping mode possibilities to be reckoned with.

Each pumping mode would have a different kinematic or performance output, and the most desirable pumping mode for one beam unit might be different from the optimum mode of another type of geometry.

Thus, evaluating the possible pumping modes for a single application, considering two or three different geometries, could become a sizeable task.

For instance, in comparing two different unit geometries for an application, one might be superior in reducing structural load, rod load range, and lift efficiency - while a second might lower torque peaks, the cyclic load factor, and surface efficiency, etc. Which is the more effective pumping mode?

Obviously, the substantial number of physical constraints on the typical well often makes the number of pumping mode options manageable - but which one is best?

To further illustrate the performance disparity of conventional unit pumping mode options, some practical, others impractical, reference is made to API bulletin 11L3 for several dramatic examples which underscore the need for some kind of rating index in addition to the regular, comprehensive, predictive survey.

EXAMPLE No. 1

On page 370 of these tables, a pumping mode using API-75 rods and pumping 8.0-300 in. SPM with an 1 1/2" plunger, the peak polished rod load is given as 20,366 lbs. To handle this same pumping application (page 373), a conventional unit using API 98 rods and pumping 11 - 100 inch SPM with a 2.75 inch plunger, will develop a peak polished rod load of 40,403 lbs. - almost exactly twice the structural load requirement when using the pumping mode employing API 75 rods. Thus, the conventional unit performs the same amount of work per day in each case, i.e. lifting 600 BFPD from 6500 feet, but by selecting the proper pumping mode, the unit structural load can be cut in half.

EXAMPLE No. 2

On page 372 of the API bulletin, it can be seen that a pumping mode of 10.4 - 300 inch SPM driving a 1.25 inch pump, with API 97 rods, develops a peak torque of 2,358,000 in-lbs to lift this same application of 600 BFPD from 6500 feet. On the preceding page (371), using API 87 rods, a conventional unit, pumping 19.9 - 64 inch SPM and driving a two inch plunger develops a peak torque of but 346,000 in-lbs.

Thus, selecting the previous pumping mode, requires a speed reducer to accommodate nearly seven times as much peak torque as is required with a second mode to handle the same pumping job. In one case, peak torque slightly overloads an API 320 in-lb reducer, while in the second case, the same pumping job requires nearly the largest beam pumping speed reducer manufactured - a 2,560,000 in-lb box. In both cases, the same amount of work is performed per day - i.e., lifting 600 barrels from 6500 feet. In this conventional unit application, one pumping mode developed a peak torque about 700% greater than that of the second pumping mode.

EXAMPLE No. 3

The desirability of selecting an optimum pumping mode is strikingly demonstrated on page 148 of the API 11L3 tables. To lift 400 b/d from 3500 feet with an API 77 rod string, lists among others, two different pumping modes, one requiring a polished rod horsepower of 57.4, another needs but 10.7. Assuming these figures are correct, rod string losses would be 118 times greater in the former pumping mode compared to the latter, and over five times as much polished rod power would be consumed by the higher horsepower mode. Furthermore, as regards only lift efficiency, which is but one of the factors involved in total system efficiency - in the 57.4 horsepower mode, about 20% of the polished rod input energy is devoted to fluid elevation, while 80% is wasted as heat loss. In the contrasting pumping mode, about 96% of the polished rod work is devoted to beneficial fluid lift, and only 4% to heat loss. This should be adequate justification for the further understanding and exploration of different beam pumping modes.

EXAMPLE No. 4

One of the most important aspects of proper pumping mode selection involves prime mover horsepower requirements.

On page 372 of the API tables, using API 97 rods and driving 10.4 - 300 in. SPM, with an 1 3/4 in. plunger, the resulting polished rod horsepower is 89.9. This number is a direct function of the size of the prime mover required. With the same API 97 rod string, it can be seen that using a 2.75 in. pump and driving 9 - 120 in. SPM, the polished rod horsepower required is 30.7 - or approximately one third the amount needed in the preceding example. Obviously, if the API 11L3 figures are correct, this means a prime mover three times as large would be required to perform the same job, when lifting 600 BFPD from 6500 feet with a conventional beam pumping unit.

Though misapplications of the magnitude of the four examples listed above seldom, if ever, occur - such disparity, even theoretical, emphasizes the fact that proper pumping mode selection can significantly increase the effectiveness and the economy of lifting fluid with a beam and sucker rod pumping system.

THE PERFORMANCE EFFECTIVENESS RATING SYSTEM (PE)

The following simple and direct mathematical model seeks to consider, balance, and harmonize most of the dominant factors concerned with performance effectiveness in lifting fluid with a beam and sucker rod system.

In this new, modified approach, called the PE model, an attempt has been made to recognize; (1) rod and structural loading; (2) rod loading alone; (3) torsional loading; (4) lift efficiency; (5) surface efficiency of the prime mover, belts, drive train and structural bearings; (6) prime mover size requirement; and (7) power consumption.

PERFORMANCE EFFECTIVENESS (PE)

$$PE = \left[\frac{W_{rf} + W_f}{PPRL} + \frac{W_{rf} + W_f}{PPRL - MPRL} + \frac{(HP_{PR})(378,150)}{(SPM)(PT_{BAL})} \right] \left(\frac{HHP}{HP_{PR}} \right) \left(0.90 \frac{\sum_{0^\circ}^{360^\circ} (746 \times \text{Output } HP_{INST})}{\sum_{0^\circ}^{360^\circ} (746 \times \text{Output } HP_{INST})} \right) \\ + M_X + (1.5) \frac{\frac{(t_1 + t_2 + t_3 \dots + t_n)}{n}}{\sqrt{\frac{t_1 + t_2 + t_3 \dots + t_n}{n}}}$$

WHERE:

W_{rf} = Weight of rods in fluid

W_f = Weight of fluid

PPRL = Peak polished rod load

MPRL = Minimum polished rod load

HP_{PR} = Polished rod horsepower

SPM = Strokes per minute

PT_{BAL} = Peak torque in balance

HHP = Hydraulic horsepower

HP_{INST} = Instantaneous horsepower

EFF_{MOTOR_INST} = Instantaneous motor efficiency

$M_X = \frac{\text{Lift Efficiency} \times \text{Surface Efficiency}}{\text{Cyclic Load Factor}}$

$t_1, t_2, t_3, \dots, t_n$ = Instantaneous torque or instantaneous motor current

n = Number of crank stations considered

In a more condensed form, the equation becomes:

$$PE = (P_X + R_X + T_X) L_X S_X + M_X + C_X$$

$$\text{WHERE: } P_X = \frac{W_{r_f} + W_f}{PPRL}$$

$$R_X = \frac{W_{r_f} + W_f}{PPRL MPRL}$$

$$T_X = \frac{(HP_{PR})(378,150)}{(SPM)(PT_{BAL})}$$

$$L_X = \frac{HHP}{HP_{PR}}$$

$$S_X = \left(.90 \frac{\sum_{0^\circ}^{360^\circ} (746 \times \text{Output HP Inst.})}{\sum_{0^\circ}^{360^\circ} (746 \times \text{Output HP Inst.})} \right) \text{ (Eff. Motor Inst.)}$$

$$M_X = \frac{(L_X)(S_X)}{CLF}$$

$$C_X = \sqrt{\frac{(t_1 + t_2 + t_3 \dots + t_n)}{\frac{(t_1 + t_2 + t_3 \dots + t_n)}{n}}} (1.5)$$

Following is a list and rationale of the various PE equation components.

1. P_X , is the structural and rod load factor, relating the dead weight of rods and fluid to the peak polished rod load. This is the reciprocal of the impulse factor used in earlier peak polished rod load formulation.
2. R_X , simply ratios the weight of rods and fluid to the load range of the system in operation.
3. T_X , is a mathematical relationship of the ratio of average torque to peak torque, modified by a constant to account for a fundamental differential in ranges between P_X , R_X , and T_X as well as attempting to balance torsional considerations properly to rod and structural factors.
4. L_X , is simply the ratio of hydraulic horsepower to polished rod horsepower, and is the quantity known as Lift Efficiency (LE).
5. S_X , is the surface efficiency of the machinery from the input of the Nema "D" motor to the output of the pumping unit. This equation for surface efficiency not only covers the mechanical efficiency of the pumping unit proper at rated capacity, or thereabouts, but also considers prime mover and belt efficiency as well.
6. M_X , is a factor based on lift efficiency, surface efficiency, and the cyclic factor, giving appropriate credit to a smaller prime mover adequately handling the required hydraulic work load.

7. C_X , is the inverse of the cyclic load factor times a 1.5 multiplier, which is a direct index of the power consumed.

Although the PE concept is primarily a performance effectiveness index, a prime mover size factor and a power consumption factor were arbitrarily added to the equation. No attempt has been made to consider either the first cost of the pumping unit and prime mover or their maintenance costs.

The larger the PE index number, the more effective the pumping mode.

Several important application functions in the optimizing of beam pumping modes can be facilitated by using the new Performance Effectiveness System (PE), or perhaps one of the three earlier optimizing versions. Because of differences in the mathematical models used, similar, though not exact correlation should be expected from the various tables.

Unfortunately, the PE system tables are not now available - but hopefully will be, sometime in the near future.

Pumping mode optimizing tables can come in at least two different arrangements, (1) having an Index number included in the regular arrangement of the tables, such as the examples in tables 1, 2, and 3; or (2) arranging the tables in either ascending or descending order according to the Indexing system used.

Pumping mode indexing tables can perform several useful functions; (1a) comparing the existing pumping mode to the optimum pumping mode to see if they are the same or similar; (2a) comparing two different pumping unit geometries using the same pumping mode to determine the difference in performance effectiveness; (3a) comparing the optimum performance effectiveness mode of one geometry to the same pumping mode of a second non-optimized geometry; (4a) to compare the optimum pumping mode of one geometry to the optimum pumping mode of another geometry, etc.

Since the new PE tables are not currently available, in the following examples, a combination of the PE model and the Lekia optimizing tables have been substituted.

Example 1a

To produce 400 barrels per day from 4000 ft. with API 76 (Grade D) rods employing a Class III beam pumping unit. The operator, using his own experience, selected a pumping mode of 16.5 - 54 inch SPM with a 2 1/2 in. plunger and 76 rods. Was this selection, based on the operator's experience, similar to the optimum pumping mode?

EXPERIENCE SELECTION

16.5 - 54 in. SPM x 2 1/2 in.

$P_X = .765$
 $R_X = .996$
 $T_X = 1.536$
 $L_X = .923$
 $S_X = .767$
 $M_X = .366$
 $C_X = .776$
 $PE = 3.476$

OPTIMUM SELECTION

13.6 - 74 in. SPM x 2.0 in.

$P_X = .7080$
 $R_X = .8780$
 $T_X = 2.296$
 $L_X = .773$
 $S_X = .750$
 $M_X = .407$
 $C_X = 1.053$
 $PE = 3.711$

Obviously, the PE's of both pumping modes are reasonably close, showing that the operator's experience has resulted in a good pumping effectiveness mode, and an economical pumping arrangement. Changing the existing pumping mode should provide a 5% or 6% improvement, which is significant enough to be considered.

Example 2a

To produce 400 B/D from 8500 ft. with API 86 Grade "D" rods. The pumping mode selected is: 12.7 - 120 in. SPM with a 1.5 in. plunger. In this case, which pumping unit geometry is the most effective - Unit "E" or Unit "F"?

Unit "E"	Unit "F"
12.7 - 120 in. SPM x 1.5 in. plunger	12.7 - 120 in. SPM x 1.5 in. plunger
PX = .695	PX = .702
RX = 1.151	RX = 1.162
TX = 1.852	TX = 2.351
LX = .719	LX = .710
SX = .779	SX = .751
MX = .339	MX = .407
CX = .909	CX = 1.145
PE = 3.319	PE = 3.798

The PE for unit "F" appears to be some 13% better than the effectiveness of unit "E", both operating with the same pumping mode. Presumably the PE is not optimum for either geometry.

Example 3a

To produce 400 B/D from 3500 ft. with API 77 rods.

The optimum pumping mode for unit "G" is; 14.6 - 64 in. SPM with a 2.0 in. plunger. A comparable unit "H" (different geometry) employs essentially the same pumping mode, except it is not known if this mode is optimum for geometry "H".

Unit "G"	Unit "H"
14.6 - 64 in. SPM x 2.0 in. plunger	14.4 - 64 in. SPM x 2.0 in. plunger
PX = .692	PX = .746
RX = .835	RX = .973
TX = 3.002	TX = 1.735
LX = .764	LX = .828
SX = .775	SX = .785
MX = .398	MX = .393
CX = 1.008	CX = .906
PE = 4.148	PE = 3.544
(OPTIMIZED)	(NOT OPTIMIZED)

In this comparison, Unit "G" optimized appears to be about 15% more effective than Unit "H", not optimized.

Example 4a

To lift 500 B/D from 4500 ft. with API 87 rods - optimumply - with unit Geometry "I", suggests a pumping mode of 17.1 - 54 in. SPM x 2.5 in. plunger, with its accompanying PE number.

Also a second PE number is desired for geometry "J" when it is operating in the identical (though non-optimized) pumping mode as Geometry "I".

And finally, a third PE number is calculated for geometry "J" when it is operating in its optimum pumping mode, and compared to Unit "I" when also optimumply driven.

Unit "I" Optimized 17.1 - 54 in. SPM x 2.5 in. plunger	Unit "J" with "I" pumping mode	Unit "J" optimized 11.8 - 86 in. SPM x 2.25 plunger
PX = .749	PX = .754	PX = .720
RX = 1.008	RX = 1.009	RX = .924
TX = 1.961	TX = 1.768	TX = 2.667
LX = .815	LX = .780	LX = .796
SX = .776	SX = .773	SX = .774
MX = .395	MX = .347	MX = .418
CX = .938	CX = .863	CX = 1.017
PE = 3.684	PE = 3.339	PE = 4.091

Although Unit "I", optimized, shows a 9.5% greater effectiveness than Unit "J" in the same pumping mode - when Unit "J"'s mode is optimized, its PE becomes 10% greater than Unit "I"'s optimized mode, and 18.5% more effective than its own non-optimized mode.

This example illustrates that a rigorous comparison of the PE for different pumping unit geometries, over a given application cannot be finally evaluated until the optimum PE for both geometries is determined and compared.

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Obviously, use of the PE procedures and other pumping mode rating systems is impractical without adequate tables.

Following are some limitations of the PE procedures: (1) it does not consider the first cost of unit, prime mover, or rod string; (2) it assumes the prime mover to be a standard, Nema D, oil field motor; (3) it does not signal overloading of the system components; (4) it assumes pumping a full barrel of incompressible fluid, off bottom each stroke.

On the other hand, if used properly, the PE system can assist in determining the optimal and most economical performance in the application of different pumping unit geometries applied to any artificial lift requirement.

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PUMP DEPTH
7500.

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Table 2a
Unit Geometry "K"

PUMP DEPTH (FT)
3000.

PUMP DISPLACEMENT (B/D) = 500.

ROD	DIA.	STROKE	SPH	PPRL	MPRL	STRESS	CLF	PT	CBM	ITE	PRHP	LE	S.EF	HPNP	CEI	GRD	N/NO	WF/SK
76	1.50	74	25.4	14144	1873	23535	1.998	253	268	26.52	27.06	40.83	78.2	69.1	1.211	62	.2875	.0748
	1.50	86	21.7	13852	1754	23048	1.728	273	301	28.49	28.89	41.08	78.2	59.5	.749	60	.2458	.0644
	1.50	100	19.1	13748	1615	22875	1.646	309	344	29.51	27.66	39.94	78.4	58.1	1.020	60	.2157	.0554
	1.50	120	15.9	14166	1418	23571	1.610	381	477	28.66	27.55	40.10	72.9	60.8	1.320	64	.1797	.0461
	1.50	144	13.2	13880	1321	23095	1.483	429	578	31.50	28.45	38.84	73.5	57.4	1.307	63	.1498	.0384
	1.75	54	27.1	13895	1331	23120	1.983	197	183	24.35	20.45	53.50	78.8	52.0	.528	63	.3048	.1380
	1.75	64	21.9	13779	1357	22926	1.676	220	212	26.01	19.91	55.50	78.5	42.5	.390	62	.2462	.1164
	1.75	74	19.1	13575	1257	22588	1.606	246	228	27.13	20.30	54.43	78.7	41.5	.409	61	.2154	.1007
	1.75	86	16.9	13702	1303	22799	1.584	284	276	27.23	20.76	53.22	74.3	44.3	.513	61	.1902	.0866
	1.75	100	14.5	13884	1484	23105	1.519	325	362	27.84	20.93	52.78	74.4	42.7	.554	62	.1636	.0745
	1.75	120	12.1	13718	1679	22825	1.434	365	468	30.56	21.51	51.35	67.9	45.5	.637	60	.1365	.0621
	1.75	144	10.1	13738	1814	22859	1.384	419	594	33.00	22.24	49.68	68.5	44.9	.722	59	.1138	.0517
	2.00	54	21.0	13880	1817	23095	1.628	187	189	27.03	16.87	65.49	76.5	35.9	.232	60	.2349	.1779
	2.00	64	17.9	13869	1700	23077	1.552	220	213	27.56	17.20	64.22	76.8	34.8	.256	61	.2003	.1501
	2.00	74	15.9	13902	1767	23132	1.516	253	248	27.22	17.41	63.44	70.8	37.3	.314	60	.1782	.1298
	2.00	86	13.4	13951	2022	23214	1.448	279	306	29.23	17.40	63.51	70.8	35.6	.317	60	.1502	.1117
	2.00	100	11.5	13867	2084	23074	1.410	313	365	30.74	17.63	62.66	71.1	35.0	.342	59	.1290	.0961
	2.00	120	9.5	13882	2250	23098	1.369	340	482	33.15	18.08	61.12	64.3	38.5	.431	58	.1068	.0801
	2.00	144	7.9	13891	2438	23113	1.336	409	615	36.37	18.65	59.23	65.0	38.4	.493	57	.0883	.0667
	2.25	54	17.8	14180	2058	23595	1.497	184	189	29.08	15.35	71.96	74.9	30.7	.149	61	.1990	.2220
	2.25	64	15.4	14458	2107	24058	1.473	227	223	27.94	15.55	71.07	75.2	30.5	.207	63	.1724	.1873
	2.25	74	13.2	14568	2280	24240	1.438	256	270	29.16	15.64	70.62	68.6	32.8	.249	63	.1474	.1620
	2.25	86	11.2	14538	2400	24190	1.400	289	315	30.74	15.76	70.09	68.8	32.1	.270	62	.1248	.1394
	2.25	100	9.5	14493	2517	24116	1.370	324	387	32.69	15.98	69.12	69.0	31.7	.296	61	.1060	.1199
	2.25	120	7.8	14511	2703	24145	1.342	373	512	35.33	16.34	67.63	62.4	35.1	.378	60	.0871	.0999
	2.50	54	15.9	15319	2414	25490	1.446	198	205	29.03	14.50	76.21	73.9	28.4	.163	68	.1773	.2706
	2.50	64	13.4	15442	2470	25694	1.436	234	239	29.46	14.67	75.33	74.1	28.4	.197	69	.1491	.2283
	2.50	74	11.1	15386	2623	25601	1.398	268	284	30.73	14.57	75.83	67.1	30.3	.231	68	.1242	.1975
	2.50	86	9.4	15375	2770	25583	1.374	304	338	32.22	14.68	75.26	67.3	30.0	.256	67	.1054	.1699
	2.50	100	8.0	15369	2902	25573	1.353	343	415	34.13	14.83	74.51	67.5	29.7	.285	66	.0889	.1461
	2.75	54	14.3	16431	2707	27340	1.420	204	216	30.19	13.96	79.13	73.2	27.1	.163	74	.1597	.3218
	2.75	64	11.7	16470	2795	27405	1.402	244	252	30.87	14.05	78.63	73.3	26.9	.193	76	.1312	.2715
	2.75	74	9.8	16495	2924	27446	1.380	284	302	31.76	14.05	78.64	66.4	29.2	.240	75	.1098	.2349
	2.75	86	8.2	16512	3053	27475	1.363	326	361	33.11	14.14	78.14	66.5	29.0	.272	75	.0923	.2021

Table 2b
Unit Geometry "L"

PUMP DEPTH (FT)
4500.

PUMP DISPLACEMENT (B/D) = 300.

ROD	DIA.	STROKE	SPH	PPRL	MPRL	STRESS	CLF	PT	CBM	ITE	PRHP	LE	S.EF	HPNP	CEI	GRD	N/NO	WF/SK
77	1.06	86	21.3	17430	3732	29001	1.661	207	430	44.19	30.99	32.08	80.7	63.8	1.194	79	.3916	.0587
	1.06	100	19.5	17161	3489	28555	1.624	246	599	42.94	32.84	30.27	81.0	65.8	1.495	78	.3580	.0504
	1.06	120	17.5	17829	3141	29666	1.625	310	736	41.60	35.83	27.75	79.7	73.0	2.368	87	.3209	.0420
	1.06	144	15.1	17875	2799	29742	1.649	346	911	44.00	36.46	27.27	79.8	75.4	2.819	89	.2771	.0350
	1.25	64	21.2	16387	3323	27266	1.393	174	290	36.15	21.20	46.90	80.6	36.7	.311	72	.3893	.1091
	1.25	74	19.5	16842	3200	28023	1.432	205	353	35.28	22.41	44.38	79.0	40.6	.453	77	.3582	.0943
	1.25	86	17.8	16804	2913	27961	1.443	236	391	35.58	23.76	41.85	79.4	43.2	.592	78	.3272	.0812
	1.25	100	16.1	17096	2916	28446	1.479	251	554	38.48	24.72	40.23	77.1	47.4	.748	81	.2961	.0698
	1.25	120	13.7	16976	3267	28246	1.453	260	715	43.46	24.65	40.35	77.1	46.5	.740	78	.2520	.0582
	1.25	144	11.4	16790	3277	27937	1.387	310	884	44.42	25.00	39.78	77.3	44.9	.814	76	.2100	.0485
	1.50	54	19.6	16610	4304	27637	1.272	142	245	37.44	16.58	59.97	79.4	26.6	.133	69	.3605	.1862
	1.50	64	17.5	16218	4069	26986	1.287	157	281	39.33	17.18	57.89	79.5	27.8	.157	67	.3219	.1571
	1.50	74	15.8	16528	3940	27501	1.364	182	345	37.91	17.38	57.22	76.9	30.8	.222	70	.2906	.1359
	1.50	86	13.9	16826	4095	27997	1.388	202	424	38.81	17.36	57.26	76.9	31.3	.259	72	.2558	.1169
	1.50	100	11.7	16770	4098	27904	1.423	207	593	45.17	17.44	57.00	77.0	32.2	.280	71	.2153	.1005
	1.50	120	10.0	16714	4130	27810	1.427	226	752	50.37	18.14	54.80	77.5	33.4	.329	71	.1839	.0838
	1.50	144	8.3	16806	4298	27964	1.410	245	955	56.76	18.39	54.06	77.7	33.4	.359	70	.1531	.0698
	1.75	54	16.8	16837	4820	28015	1.395	139	242	38.53	14.31	69.48	78.7	25.4	.119	68	.3092	.2534
	1.75	64	14.7	17561	4641	29220	1.435	164	327	37.33	14.30	69.54	78.7	26.1	.155	75	.2694	.2138
	1.75	74	12.6	17448	4528	29032	1.469	129	419	55.15	14.32	69.42	78.7	26.7	.128	75	.2318	.1849
	1.75	86	10.7	17181	4708	28587	1.499	165	471	51.38	14.47	68.74	78.8	27.5	.170	71	.1973	.1591
	1.75	100	9.4	17487	4641	29096	1.542	210	627	47.63	14.99	66.32	74.5	31.0	.266	75	.1728	.1368
	1.75	120	7.8	17347	4896	28863	1.533	218	796	55.99	15.08	65.92	74.6	31.0	.274	72	.1427	.1140
	2.00	54	14.8	18222	5251	30320	1.694	81	342	67.10	12.95	76.81	79.8	27.5	.090	78	.2727	.3310
	2.00	64	12.7	18410	5075	30633	1.662	120	383	54.11	13.08	76.05	79.8	27.2	.132	81	.2326	.2793
	2.00	74	10.5	18221	5226	30318	1.673	154	414	50.63	13.01	76.42	77.8	28.0	.173	78	.1922	.2415
	2.00	86	9.0	18447	5171	30694	1.712	197	485	46.72	13.23	75.17	72.1	31.4	.261	81	.1656	.2078
	2.25	54	14.1	19655	5880	32704	2.057	92	352	62.68	12.97	76.68	79.8	33.4	.163	89	.2583	.4189
	2.25	64	11.3	19807	5560	32957	1.954	141	400	49.77	12.63	78.76	77.4	31.9	.222	93	.2073	.3535
	2.25	74	9.2	19560	5530	32545	1.938	179	426	47.67	12.46	79.81	70.9	34.1	.290	90	.1687	.3057

ROD NO.	PUMP DEPTH (FT)	PUMP DISPLACEMENT (B/D)	WFL/SK
76	5000.	600.	
SROKE	100	ITE	HPMP
SPM	124	9.4F	LE
PRRL	100	PRHP	PT
MPRL	100	CBM	GRDD
STRESS	100	GRDC	STRESS
MPRL	100	STRESS	MPRL
PRRL	100	PRRL	PRRL
SPM	100	SPM	SPM
SROKE	100	SROKE	SROKE
DTA	100	DTA	DTA

[illegible]